

Learning linear operators: Infinite-dimensional regression as a well-behaved non-compact inverse problem

Mattes Mollenhauer¹

Nicole Mücke²

T. J. Sullivan^{3,4}

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¹Freie Universität Berlin, DE

²Technische Universität Braunschweig, DE

³**University of Warwick, UK**

⁴**Alan Turing Institute, UK**

For all the details:



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Problem statement

- Let X and Y be Bochner square-integrable random variables taking values in separable Hilbert spaces \mathcal{X} and \mathcal{Y} respectively, i.e. $(X, Y) \in L^2(\mathbb{P}; \mathcal{X} \times \mathcal{Y})$.
- We aim to solve the following **regression problem**:

$$\text{minimise } \mathbb{E}[\|Y - \theta X\|_{\mathcal{Y}}^2] \equiv \|Y - \theta X\|_{L^2(\mathbb{P}; \mathcal{Y})}^2 \text{ w.r.t. } \theta \in L(\mathcal{X}, \mathcal{Y}), \quad (\text{RP})$$

where $L(\mathcal{X}, \mathcal{Y})$ is the Banach space of bounded linear operators from \mathcal{X} into \mathcal{Y} .

- In practice, we will only have data points (X_i, Y_i) , $i = 1, \dots, n$ — so we must think about empirical approximation and regularisation.
- **Moral of the talk:** From a regularisation standpoint, (RP) is “just as hard” as finite-dimensional regression in reasonable settings.

Motivating instances of the problem

- If at least one of \mathcal{X} and \mathcal{Y} has infinite dimension, then so too does the search space $L(\mathcal{X}, \mathcal{Y})$, and so (RP) is an **infinite-dimensional regression problem**.
- We are particularly motivated by the case of infinite-dimensional \mathcal{Y} , exemplified by relevant applications in
 - **functional linear regression with functional response** (Ramsay and Silverman, 2005);
 - non-parametric regression with **vector-valued kernels** (Caponnetto and De Vito, 2007) (more on this in a moment);
 - the **conditional mean embedding** (Park and Muandet, 2020; Li et al., 2022);
 - and inference for **Hilbertian time series** (Bosq, 2000).

Example: (Vector-valued) kernel regression 1

- Let \mathcal{E} be a second-countable locally compact Hausdorff space equipped with its Borel σ -algebra $\mathcal{B}_{\mathcal{E}}$, and let \mathcal{X} be an RKHS of \mathbb{R} -valued functions on \mathcal{E} with reproducing kernel $k: \mathcal{E}^2 \rightarrow \mathbb{R}$ and canonical feature map $\varphi: \mathcal{E} \rightarrow \mathcal{X}$.
- Assume further that $(\mathcal{E}, \mathcal{B}_{\mathcal{E}})$ is equipped with a probability measure μ , with a **compact embedding operator** $i: \mathcal{X} \hookrightarrow L^2(\mu)$ (e.g. [Christmann and Steinwart, 2008](#), Section 4.3).
- Let \mathcal{Y} be another separable real Hilbert space. Consider $\mathcal{G} := \{A\varphi(\cdot) \mid A \in S_2(\mathcal{X}, \mathcal{Y})\}$; this is a **vv-RKHS** of \mathcal{Y} -valued functions with operator-valued reproducing kernel

$$\begin{aligned} K: \mathcal{E}^2 &\rightarrow L(\mathcal{Y}) \\ (x, x') &\mapsto k(x, x') \text{Id}_{\mathcal{Y}} \end{aligned}$$

and we have a bounded linear embedding operator

$$I := i \otimes \text{Id}_{\mathcal{Y}}: \mathcal{G} \cong \mathcal{X} \otimes \mathcal{Y} \hookrightarrow L^2(\mu) \otimes \mathcal{Y} \cong L^2(\mu; \mathcal{Y}).$$

As the embedding $i: \mathcal{X} \hookrightarrow L^2(\mu)$ is compact, the embedding $I := i \otimes \text{Id}_{\mathcal{Y}}$ is compact $\iff \dim \mathcal{Y} < \infty$.

Example: (Vector-valued) kernel regression 2

- We now consider an \mathcal{E} -valued random variable ξ with law $\mathcal{L}(\xi) =: \mu$ on $(\mathcal{E}, \mathcal{B}_{\mathcal{E}})$ and a \mathcal{Y} -valued random variable Y , both defined on a common probability space.
- The **nonlinear kernel regression problem**

$$\min_{F \in \mathcal{G}} \mathbb{E}[\|Y - F(\xi)\|_{\mathcal{Y}}^2]$$

is equivalent to the (Hilbert–Schmidt) version of the **linear regression problem** (RP) with $X := \varphi(\xi)$:

$$\min_{\theta \in \mathcal{S}_2(\mathcal{X}, \mathcal{Y})} \mathbb{E}[\|Y - \theta\varphi(\xi)\|_{\mathcal{Y}}^2].$$

Problem reformulation

The problem with infinite-dimensional regression

- Infinite-dimensional linear regression **does not necessarily admit a minimiser!**
- Assuming a **well-specified linear model**, i.e. the existence of a bounded linear operator $\theta_\star: \mathcal{X} \rightarrow \mathcal{Y}$ such that

$$Y = \theta_\star X + \varepsilon$$

with an exogeneous \mathcal{Y} -valued noise variable ε satisfying $\mathbb{E}[\varepsilon|X] = 0$, (RP) is equivalent to the **operator factorisation problem**

$$C_{YX} = \theta C_{XX}, \quad \theta \in L(\mathcal{X}, \mathcal{Y}), \quad (\text{OFP})$$

where $C_{YX} \in L(\mathcal{X}, \mathcal{Y})$ and $C_{XX} \in L(\mathcal{X}, \mathcal{X})$ are the **covariance operators** (Baker, 1973) associated with X and Y .

- Solubility of (OFP) is related to a well-known set of *range inclusion* and *operator majorisation* conditions due to Douglas (1966) and the *Moore–Penrose pseudoinverse* (Engl et al., 1996).

Recap: Tensor products and covariance operators

- For $y \in \mathcal{Y}$ and $x \in \mathcal{X}$, $y \otimes x \in L(\mathcal{X}, \mathcal{Y})$ is the **rank-one operator**

$$\mathcal{X} \ni v \mapsto (y \otimes x)(v) := \langle x, v \rangle_{\mathcal{X}} y \in \mathcal{Y}.$$

- The **Hilbert tensor product** $\mathcal{Y} \otimes \mathcal{X}$ is defined to be the completion of the linear span of all such rank-one operators w.r.t. $\langle y \otimes x, y' \otimes x' \rangle_{\mathcal{Y} \otimes \mathcal{X}} := \langle y, y' \rangle_{\mathcal{Y}} \langle x, x' \rangle_{\mathcal{X}}$.
- Note that $\mathcal{Y} \otimes \mathcal{X}$ is isometric with $S_2(\mathcal{X}, \mathcal{Y})$, the space of **Hilbert–Schmidt operators**; and also $L^2(\mathbb{P}; \mathcal{X}) \cong L^2(\mathbb{P}; \mathbb{R}) \otimes \mathcal{X}$.
- The (uncentred) **covariance operators** (Baker, 1973) of Y with X , and of X with itself, are given by

$$\text{Cov}[Y, X] := C_{YX} := \mathbb{E}[Y \otimes X] \in S_1(\mathcal{X}, \mathcal{Y}) = \{\text{trace-class op's}\} \quad \text{and}$$

$$\text{Cov}[X, X] := C_{XX} := \mathbb{E}[X \otimes X] \in S_1(\mathcal{X}).$$

- Note that $C_{YX}^* = C_{XY}$, and so C_{XX} is self-adjoint.
- The covariance operators are the unique operators satisfying

$$\mathbb{E}[\langle y, Y \rangle_{\mathcal{Y}} \langle x, X \rangle_{\mathcal{X}}] = \langle y, C_{YX} x \rangle_{\mathcal{Y}} \quad \text{for all } x \in \mathcal{X}, y \in \mathcal{Y}.$$

From operator factorisation to a non-compact linear inverse problem

- The operator factorisation problem (OFP)

$$C_{YX} = \theta C_{XX}, \quad \theta \in L(\mathcal{X}, \mathcal{Y}), \quad (\text{OFP})$$

can be reformulated in terms of a (potentially ill-posed) **linear inverse problem**

$$A_{C_{XX}}[\theta] = C_{YX}, \quad \theta \in L(\mathcal{X}, \mathcal{Y}) \quad (\text{IP})$$

based on the (**generally non-compact**) **forward operator** $A_{C_{XX}} : L(\mathcal{X}, \mathcal{Y}) \rightarrow L(\mathcal{X}, \mathcal{Y})$,

$$A_{C_{XX}}[\theta] := \theta C_{XX}.$$

- We call the operator $A_{C_{XX}}$ the **precomposition operator** associated with C_{XX} .
- **Even in the misspecified case**, the solution to the inverse problem (IP) still characterises the minimiser of the linear regression problem (RP)!

Spectral theory and regularisation

Naïve solution of the inverse problem

- The standard, naïve thing to do at this point would be to solve (IP)

$$A_{C_{XX}}[\theta] = C_{YX}, \quad \theta \in L(\mathcal{X}, \mathcal{Y})$$

using the Moore–Penrose pseudoinverse of $A_{C_{XX}}$:

$$\theta = A_{C_{XX}}^\dagger [C_{YX}].$$

- The **problem** is that $\dim \mathcal{Y} = \infty \implies A_{C_{XX}}$ is non-compact, in which case we have no good off-the-shelf spectral theory for $A_{C_{XX}}$, no pseudoinverse, etc.
- Fortunately, we can build a **decent spectral theory** for $A_{C_{XX}}$ if we focus on the **Hilbert–Schmidt setting**: we restrict the search to $\theta \in S_2(\mathcal{X}, \mathcal{Y})$ and use the fact that

$$A_{C_{XX}} : S_2(\mathcal{X}, \mathcal{Y}) \rightarrow S_2(\mathcal{X}, \mathcal{Y}).$$

Theorem 1 (Spectral decomposition)

Let $C \in S_2(\mathcal{X})$ be self-adjoint with spectral decomposition

$$C = \sum_{\lambda \in \sigma_p(C)} \lambda P_{\text{eig}_\lambda(C)},$$

where $P_{\text{eig}_\lambda(C)}: \mathcal{X} \rightarrow \mathcal{X}$ is orthogonal projection onto $\text{eig}_\lambda(C)$ and the above series expression converges in operator norm. Then the **non-compact** induced precomposition operator A_C on $S_2(\mathcal{X}, \mathcal{Y})$ has **pure point spectrum** and the spectral decomposition

$$A_C = \sum_{\lambda \in \sigma_p(C)} \lambda P_{\mathcal{Y} \otimes \text{eig}_\lambda(C)},$$

where $P_{\mathcal{Y} \otimes \text{eig}_\lambda(C)}: S_2(\mathcal{X}, \mathcal{Y}) \rightarrow S_2(\mathcal{X}, \mathcal{Y})$ is orthogonal projection onto $\mathcal{Y} \otimes \text{eig}_\lambda(C)$ and the above series converges in operator norm.

Spectral theory for precomposition operators 2

Corollary 2 (Compatibility with functional calculus)

Let $C = \sum_{\lambda \in \sigma_p(C)} \lambda P_{\text{eig}_\lambda(C)} \in S_2(\mathcal{X})$ be self-adjoint. If $g: \mathbb{R} \rightarrow \mathbb{R}$ is extended to act on self-adjoint Hilbert space operators with pure point spectrum in terms of their spectral decompositions via

$$g(C) := \sum_{\lambda \in \sigma_p(C)} g(\lambda) P_{\text{eig}_\lambda(C)},$$

then A_C as an operator on $S_2(\mathcal{X}, \mathcal{Y})$ satisfies

$$A_{g(C)} = g(A_C) = \sum_{\lambda \in \sigma_p(C)} g(\lambda) P_{\mathcal{Y} \otimes \text{eig}_\lambda(C)},$$

We will use this with $g = g_\alpha$ being some approximation — e.g. Tikhonov, spectral cutoff, ... — to the ‘ideal’ inverse $g(\lambda) = \lambda^{-1}$, yielding a **regularised population solution** to (IP):

$$\theta_\alpha := g_\alpha(A_{C_{XX}})[C_{YX}] = C_{YX} g_\alpha(C_{XX}).$$

Terminology for regularisation

- A family of functions $g_\alpha: [0, \infty) \rightarrow \mathbb{R}$, indexed by a **regularisation parameter** $\alpha > 0$, is a **spectral regularisation strategy** (Engl et al., 1996) if

$$(R1) \quad \sup_{\lambda \in [0, \infty)} |\lambda g_\alpha(\lambda)| \leq D \text{ for some constant } D,$$

$$(R2) \quad \sup_{\lambda \in [0, \infty)} |1 - \lambda g_\alpha(\lambda)| \leq \gamma_0 \text{ for some constant } \gamma_0, \text{ and}$$

$$(R3) \quad \sup_{\lambda \in [0, \infty)} |g_\alpha(\lambda)| < B\alpha^{-1}, \text{ for some constant } B.$$

- We write $r_\alpha(\lambda) := 1 - \lambda g_\alpha(\lambda)$ for the **residual** associated to the regularisation scheme g_α .
- The **qualification** of g_α is the maximal q such that

$$\sup_{\lambda \in [0, \infty)} \lambda^q |r_\alpha(\lambda)| \equiv \sup_{\lambda \in [0, \infty)} \lambda^q |1 - \lambda g_\alpha(\lambda)| \leq \gamma_q \alpha^q$$

for some constant γ_q which does not depend on α .

- Such assumptions are also common in learning theory (see e.g. Bauer et al., 2007; Gerfo et al., 2008; Dicker et al., 2017; Blanchard and Mücke, 2018).

Regularised empirical solutions

Empirical solutions

- X and Y are in practice only accessible through sample pairs $(X_i, Y_i) \in \mathcal{X} \times \mathcal{Y}$ for $i = 1, \dots, n$.
- For simplicity, we assume that these sample pairs are obtained i.i.d. from the joint law of (X, Y) .
- We define the **empirical covariance operators** by

$$\widehat{C}_{XX} := \frac{1}{n} \sum_{i=1}^n X_i \otimes X_i \text{ and } \widehat{C}_{YX} := \frac{1}{n} \sum_{i=1}^n Y_i \otimes X_i.$$

- Note that \widehat{C}_{XX} and \widehat{C}_{YX} are \mathbb{P} -a.s. of rank at most n .
- We now analyse the **regularised empirical solution**

$$\widehat{\theta}_\alpha := g_\alpha(A_{\widehat{C}_{XX}})[\widehat{C}_{YX}] = \widehat{C}_{YX} g_\alpha(\widehat{C}_{XX}). \quad (\text{EMP})$$

- We can obtain rates for Hilbert–Schmidt regression based on Hölder source conditions.
- We analyse the error $\theta_\star - \hat{\theta}_\alpha$ associated with the regularised empirical solution $\hat{\theta}_\alpha$.
- In particular, we are interested both in the Hilbert–Schmidt norm of this error and in the mean-square prediction error

$$\mathbb{E}[\|(\theta_\star - \hat{\theta}_\alpha)X\|_{\mathcal{Y}}^2] \equiv \|(\theta_\star - \hat{\theta}_\alpha)C_{XX}^{1/2}\|_{S_2(\mathcal{X},\mathcal{Y})}^2.$$

- To treat these in a unified way we will examine

$$\|(\theta_\star - \hat{\theta}_\alpha)C_{XX}^s\|_{S_2(\mathcal{X},\mathcal{Y})} \text{ for } 0 \leq s \leq \frac{1}{2}.$$

Hölder source conditions

To establish quantitative convergence rates, we need a priori assumptions on the “smoothness” of the ground truth θ_* , a.k.a. “source conditions”:

Assumption 3

We assume that the solution satisfies the **Hölder source condition** $\theta_* \in \Omega(\nu, R)$, where

$$\Omega(\nu, R) := \{A_{\mathcal{C}_{XX}}^\nu[\theta] \mid \theta \in \mathcal{S}_2(\mathcal{X}, \mathcal{Y}), \|\theta\|_{\mathcal{S}_2(\mathcal{X}, \mathcal{Y})} \leq R\} \subseteq \mathcal{S}_2(\mathcal{X}, \mathcal{Y}).$$

Lemma 4

The source condition $\theta_* \in \Omega(\nu, R)$ holds if and only if the **moment condition**

$$\sum_{i \in I} \sup_{x \in \mathcal{X}} \frac{|\mathbb{E}[\langle x, X \rangle_{\mathcal{X}} \langle e_i, Y \rangle_{\mathcal{Y}}]|^2}{\|\mathcal{C}_{XX}^{\nu+1} x\|_{\mathcal{X}}^2} \leq R^2$$

hold for some (indeed, any) complete orthonormal system $\{e_i\}_{i \in I}$ in \mathcal{Y} .

Decomposing the error 1/2

- Naïve error decomposition: $\mathbb{P}^{\otimes n}$ -a.s. with respect to the samples $(X_i, Y_i)_{i=1}^n$,

$$\|(\theta_\star - \hat{\theta}_\alpha) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})} \leq \underbrace{\|(\theta_\star - \theta_\alpha) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})}}_{=\text{approximation error}} + \underbrace{\|(\theta_\alpha - \hat{\theta}_\alpha) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})}}_{=\text{variance}}. \quad (3.1)$$

- However, this decomposition turns out to be less than ideal and instead we use:

$$\begin{aligned} \theta_\star - \hat{\theta}_\alpha &= \theta_\star - \theta_\star \hat{C}_{XX} g_\alpha(\hat{C}_{XX}) + \theta_\star \hat{C}_{XX} g_\alpha(\hat{C}_{XX}) - \hat{\theta}_\alpha \\ &= \theta_\star r_\alpha(\hat{C}_{XX}) + \theta_\star \hat{C}_{XX} g_\alpha(\hat{C}_{XX}) - \hat{C}_{YX} g_\alpha(\hat{C}_{XX}) \\ &= \theta_\star r_\alpha(\hat{C}_{XX}) + (\theta_\star \hat{C}_{XX} - \hat{C}_{YX}) g_\alpha(\hat{C}_{XX}). \end{aligned}$$

- Hence, $\mathbb{P}^{\otimes n}$ -a.s.,

$$\|(\theta_\star - \hat{\theta}_\alpha) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})} \leq \|\theta_\star r_\alpha(\hat{C}_{XX}) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})} + \|(\theta_\star \hat{C}_{XX} - \hat{C}_{YX}) g_\alpha(\hat{C}_{XX}) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})}.$$

- Hence, $\mathbb{P}^{\otimes n}$ -a.s.,

$$\begin{aligned} \|(\theta_\star - \hat{\theta}_\alpha) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})} &\leq \| \theta_\star r_\alpha(\hat{C}_{XX}) C_{XX}^s \|_{S_2(\mathcal{X}, \mathcal{Y})} \\ &\quad + \|(\theta_\star \hat{C}_{XX} - \hat{C}_{YX}) g_\alpha(\hat{C}_{XX}) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})}. \end{aligned} \quad (3.2)$$

- Again, we think of the two terms on the right-hand side of (3.2) as an **approximation error** and a **variance term**.
- Crucially, though, the approximation error in the decomposition (3.2) is random — as opposed to the deterministic approximation term in (3.1) — and both terms in (3.2) will be amenable to analysis using concentration-of-measure techniques.

Hilbert space concentration bounds

The key tool for us is a recent **concentration inequality** for Hilbert space-valued random variables:

Theorem 5 (Maurer and Pontil, 2021, Prop. 7.11)

Let ξ, ξ_1, \dots, ξ_n be i.i.d. random variables with joint law $\mathbb{P}^{\otimes n}$ taking values in a separable Hilbert space \mathcal{H} such that $\mathbb{E}[\xi] = 0$ and the **subexponential norm** $\|\xi\|_{L_{\psi_1}(\mathbb{P}; \mathcal{H})}$ is finite. Then, for all $\delta \in (0, \frac{1}{2}]$ and $n \geq \log(1/\delta)$, with $\mathbb{P}^{\otimes n}$ -probability at least $1 - \delta$,

$$\left\| \frac{1}{n} \sum_{i=1}^n \xi_i \right\|_{\mathcal{H}} \leq 8\sqrt{2}e \|\xi\|_{L_{\psi_1}(\mathbb{P}; \mathcal{H})} \sqrt{\frac{\log(1/\delta)}{n}}.$$

Despite the large number of terms that we need to bound, we carefully reduce the number of independent appeals to Maurer and Pontil (2021) to a minimum of only **two**.

Subexponential and sub-Gaussian norms

- For a real-valued random variable ξ defined on $(\Omega, \mathcal{F}, \mathbb{P})$, we introduce the Banach spaces $L_{\psi_1}(\Omega, \mathcal{F}, \mathbb{P}; \mathbb{R}) = L_{\psi_1}(\mathbb{P})$ and $L_{\psi_2}(\Omega, \mathcal{F}, \mathbb{P}; \mathbb{R}) = L_{\psi_2}(\mathbb{P})$ via the norms

$$\text{subexponential:} \quad \|\xi\|_{L_{\psi_1}(\mathbb{P})} := \sup_{1 \leq p < \infty} \frac{\|\xi\|_{L^p(\mathbb{P})}}{p},$$

$$\text{sub-Gaussian:} \quad \|\xi\|_{L_{\psi_2}(\mathbb{P})} := \sup_{1 \leq p < \infty} \frac{\|\xi\|_{L^p(\mathbb{P})}}{p^{1/2}}.$$

- For ξ taking values in a separable Hilbert space \mathcal{H} :

$$\|\xi\|_{L_{\psi_1}(\mathbb{P}; \mathcal{H})} := \|\|\xi\|_{\mathcal{H}}\|_{L_{\psi_1}(\mathbb{P})} = \sup_{1 \leq p < \infty} \frac{\|\xi\|_{L^p(\mathbb{P}; \mathcal{H})}}{p}$$

and analogously for $\|\xi\|_{L_{\psi_2}(\mathbb{P}; \mathcal{H})} := \|\|\xi\|_{\mathcal{H}}\|_{L_{\psi_2}(\mathbb{P})}$.

Convergence rates

Theorem 6 (Convergence rates under Hölder source conditions)

Suppose that g_α has qualification $q \geq \nu + s$. Suppose that $Y \in L_{\psi_2}(\mathbb{P}; \mathcal{Y})$, $X \in L_{\psi_2}(\mathbb{P}; \mathcal{X})$, $\theta_\star \in \Omega(\nu, R)$, and $0 < \alpha < 1$. Let $\delta \in (0, \frac{1}{e}]$ and $s \in [0, \frac{1}{2}]$. For the regularisation schedule

$$\alpha_n := \left(\frac{1}{\sqrt{n}} \right)^{\frac{1}{\nu+1}},$$

and for

$$n \geq n_0 := \max \left\{ \|X\|_{L_{\psi_2}(\mathbb{P}; \mathcal{X})}^4, \left(1152e^2 \|X\|_{L_{\psi_2}(\mathbb{P}; \mathcal{X})}^4 \log(1/\delta) \right)^{\frac{1}{\nu}} \right\}^{1+\nu},$$

with $\mathbb{P}^{\otimes n}$ -probability at least $1 - 2\delta$,

$$\|(\theta_\star - \hat{\theta}_{\alpha_n}) C_{XX}^s\|_{S_2(\mathcal{X}, \mathcal{Y})} \leq 3\bar{\kappa} \sqrt{\log(1/\delta)} \left(\frac{1}{\sqrt{n}} \right)^{\frac{s+\nu}{1+\nu}},$$

where $\bar{\kappa}$ is an explicit constant depending only on the regularisation scheme, the source condition, and the sub-Gaussian norms of X and Y .

Optimal rates and comparison to kernel setting

- The rates in Theorem 6 match those of kernel regression with scalar and finite-dimensional response variables under a Hölder source condition and with no additional assumptions on the eigenvalue decay of C_{XX} (Caponnetto and De Vito, 2007; Blanchard and Mücke, 2018; Lin et al., 2020).
- **Minimax optimality of these rates** is only derived by Caponnetto and De Vito (2007) and Blanchard and Mücke (2018) under the additional assumption that the eigenvalues of C_{XX} decay rapidly enough, which is an implicit assumption on the marginal distribution of X .
- To establish minimax optimality in our setting, we would have to repeat the standard arguments, e.g. apply a general reduction scheme in conjunction with Fano's method (Tsybakov, 2009).
- However, as discussed earlier, the Hilbert–Schmidt regression problem has scalar response kernel regression and some settings of **kernel regression with vector-valued response as special cases**.

Closing remarks

Open questions

- Can we obtain **fast $1/n$ rates**? This would require additional assumptions about the joint law of (X, Y) . So far, this is only solved for the special case of the CME (Li et al., 2022).
- Solving (RP)/(IP) over the **non-reflexive Banach space** $L(\mathcal{X}, \mathcal{Y})$ — a simple yet really evil example is $\mathcal{X} = \mathcal{Y}$ and $\theta_* = \text{Id}$.
- Learning in $L(\mathcal{X}, \mathcal{Y})$ requires **more general source conditions**, since the Hölder source condition $\theta_* = \tilde{\theta} C_{XX}^\nu$ with $\tilde{\theta} \in L(\mathcal{X}, \mathcal{Y})$ already implies the Hilbert–Schmidt setting $\theta_* \in S_2(\mathcal{X}, \mathcal{Y})$ for $\nu > \frac{1}{2}$.
- For Banach space \mathcal{X} and \mathcal{Y} , a **suitable analogue of (IP)** is needed. The Hilbert case uses $\text{tr}(C_{XX}) = \mathbb{E}[\|X\|_{\mathcal{X}}^2]$ and derivative of squared norm.
- Extension to more **general non-i.i.d. sample data**, e.g. autoregression for stationary time series?

Thank You!



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